

Using Mobile Apps to Enhance Learning in Differential Equations

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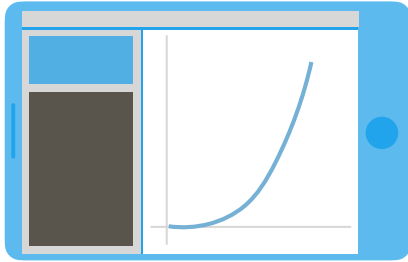
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Check out the apps at

<http://www.slopesapp.com>

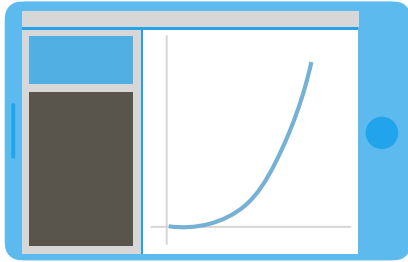
<http://www.wavespdeapp.com>





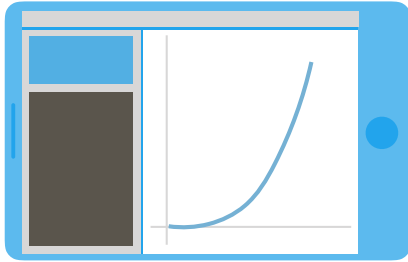
Class Approach

- * Physical assumptions
- * Mathematical expressions
- * Think before you solve
 - * Equilibrium solutions
 - * Graphical analysis
 - * Slopefields, Phase Planes, etc
- * Analytical Solutions



App Information

- * Languages: **Swift and Kotlin**
- * Platforms: **iOS and Android**
- * <http://slopesapp.com> (ODE)
 - * iPad Release: **Nov 2016**
 - * iPhone Release: **July 2017**
 - * Android Release: **Jan 2021**
- * <http://wavespdeapp.com> (PDE)
 - * iOS Release Date: **June 2019**

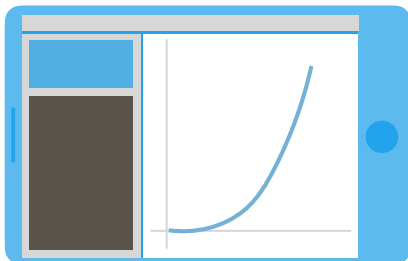


Why Mobile Devices?

- * Portable
- * Comparatively large screen
- * Tactile interface

The Role of iPads in Constructing Collaborative Learning Spaces (Fisher, Lucas and Galstyan, 2013)

Using Slopes to Enhance Learning in Ordinary Differential Equations (K. Lucas and T. Lucas, 2020)



Semester Projects

- * Main Goal: Understand and analyze a mathematical model using techniques learned in class
 - * Slopefields/Phase Planes, Equilibrium Analysis, Numerical/Algebraic Solutions, ...
- * Teams of 3-4 Students
- * Final Poster Presentation
 - * Judged by math and science faculty
- * Images provided by Slopes



Mountain Lions vs. Deer

Three Models Examining Predator Prey Dynamics



Background

Over the last 16 months, Pepperdine has issued 17 warnings regarding mountain lions spotted on campus. In an effort to understand the dynamics behind this rise in sightings (and the Malibu ecosystem in general), we use predator/prey systems of differential equations. Within California, mountain lions feed primarily on deer, and deer are preyed on primarily by mountain lions. Given the omnipresent nature of deer on campus, this likely extends to our local ecosystem. We aim to better understand this relationship, we compare three predator/prey models with increasing complexity.

Basic Model and Coefficient Estimates

In its most nascent form, our model includes two species (mountain lions and deer), and models deer using exponential growth. The variables x and y represent deer (prey) and mountain lion (predator) populations, respectively. The equations are displayed below.

$$\begin{aligned}x' &= ax - bxy \\ y' &= -cy + dxy\end{aligned}$$

Coefficients:

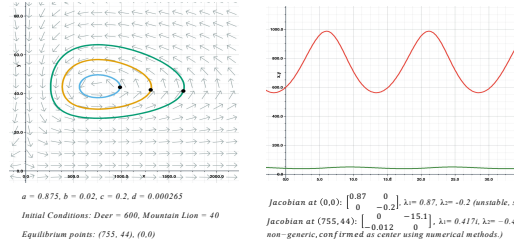
a	Rate of growth without predation.
b	Rate at which predation (interactions) decreases deer population.
c	Rate at which mountain lions die without prey.
d	Rate at which predation (interaction) increases mountain lion population.

While the true values of some parameters are unknown, zoological research can be used to guide many of these choices:

- Deer's maximum growth rate is estimated using reproduction statistics.
 - At any given time, 66% of female deer are pregnant. Deer have an average litter size of 1.9, are pregnant for about 203 days, and exhibit balanced sex ratios.
- If we observed a deer population and returned 203 days later, we would therefore expect to see 62.7% more deer. Therefore, without external constraints the population will grow according to the equation $x = ce^{0.875t}$, with c denoting the starting population, and t denoting change in time (in years).
- The location of equilibriums is estimated using food intake requirements.
 - Should the growth in the deer population produce exactly the amount of meat required to sustain the mountain lion population, no change should occur in either.
- The average mountain lion requires 6.57 pounds of meat per day to survive. As the average mule deer weighs 177 pounds, with at most 133 pounds being edible biomass, a mountain lion's survival requires 0.049 deer per day, which is 18.0 per year.

First Model Behavior

The phase plane has two equilibrium points: a saddle point at $(0,0)$ and a center at $(c/d, a/b)$. Only in cases of complete extinction and at $(c/d, a/b)$ are both populations at rest. A phase plane is shown below, along with a graph of each population. Coefficients were informed by the research described above. Except in the case when an initial value is zero, populations continuously orbit around the center.



Logistic Growth and Ratio Dependence

Our second model introduces the concepts of logistic growth and density dependence. The equations are displayed below.

$$\begin{aligned}x' &= ax \left(1 - \frac{x}{k}\right) - \frac{bxy}{(1 + fx + y)} \\ y' &= -cy + \frac{dxy}{(1 + fx + y)}\end{aligned}$$

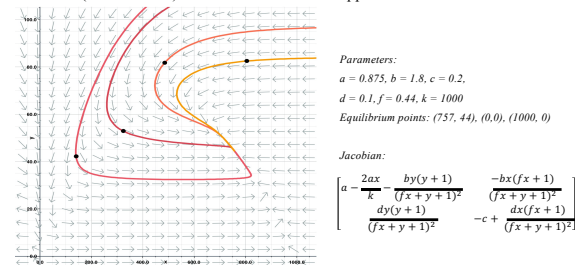
Logistic growth is introduced by the addition of $(1-x/k)$ to the part of the equation controlling deer growth. This takes resource scarcity into account, and ensures that the deer population do not expand beyond its carrying capacity (k). The importance of this feature is highlighted by a potential behavior observable in the first model: without mountain lions the deer population will expand infinitely. While California's natural carrying capacity for deer is an unexpectedly contentious topic, the deer population peaked at approximately 2 million before declining substantially to its current level of 540,000.

Density dependence is introduced by the denominator now beneath both interaction terms. The effect of this change is best explained by an example. Say that an environment has 100 deer and 1 mountain lion. Say that a second environment has 10 deer and 10 mountain lions. Under our first model, both interaction terms end up the same: 100 times some interaction coefficient. This is obviously a departure from how deer and mountain lions interact in reality. Thus, the new model makes the effectiveness of predation dependent on this ratio between species. The most effective ratio can be determined using the value the coefficients (in this case just f , as one can always be omitted). For example, if $f = 1$, the second environment would yield a larger interaction term under the new model.

To ensure comparability between models, values of coefficients representing biological constants (a, c) remain unchanged from the previous model, and interaction coefficients (b, d) are appropriately scaled to adjust for the new model.

Second Model Behavior

The phase plane of the second model is shown below. As the model is not linear, the Jacobian (matrix below) serves as a useful linear approximation.



Using this Jacobian, the equilibrium points can be categorized. The Jacobian for the only equilibrium where both species survive is shown below, along with the useful indicators it provides.

$$J = \begin{bmatrix} -0.45896 & -3.1775 \\ 0.0014 & -0.2347 \end{bmatrix} \quad \begin{aligned} \lambda_1 &= -0.257 & \text{tr}(J) &= -0.694 \\ \lambda_2 &= -0.437 & \det(J) &= 0.112 \end{aligned}$$

This makes (757, 44) a nodal sink (stable). Using the same techniques, (0,0) and (1000, 0) can both be categorized as saddle points.

When initial populations are non-zero, they will eventually sink into a single equilibrium of 757 deer and 44 mountain lions. Unlike the previous model, the equilibrium is always approached (nodal sink) rather than circled around (center).

Adding a Third Species

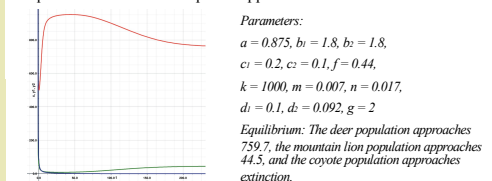
When compared to empirical data, it becomes clear that both models discussed though this point are incomplete. Just 5,000 wild mountain lions roam California—well below what our two-species model predicts. While a wildlife policy of suppressing dangerous mountain lions while protecting deer from predation is likely the largest culprit, it is also worth considering other interactions within our ecosystem. Our third and final model maintains the concepts discussed in its antecedent while adding a third species: coyotes. The equations are displayed below, with y_1 denoting mountain lions and y_2 denoting coyotes.

$$\begin{aligned}x' &= ax \left(1 - \frac{x}{k}\right) - \frac{b_1xy_1}{(1 + fx + y_1 + gy_2)} - \frac{b_2xy_2}{1 + fx + y_1 + gy_2} \\ y_1' &= -c_1y_1 - my_1y_2 + \frac{d_1xy_1}{(1 + fx + y_1 + gy_2)} \\ y_2' &= -c_2y_2 - ny_1y_2 + \frac{d_2xy_2}{(1 + fx + y_1 + gy_2)}\end{aligned}$$

Most new parameters are direct extensions of the previous model (b_2, c_2, d_2). The new term gy_2 in each denominator generalizes the ratio to consider all three species. New interaction terms between mountain lions and coyotes are also included (my_1y_2, ny_1y_2). Coyotes live in the same environments as mountain lions, and consume the same prey (deer). As mountain lions and coyotes are directly antagonistic to each other (beyond the indirect effects of consuming deer), both coefficients are negative. As mountain lions are far larger predators than coyotes (137 pounds vs 31 pounds), it can be assumed that n is the larger coefficient.

Third Model Behavior

A plot of all three populations is shown below. Using our starting conditions and parameters (as well as reasonable variations thereof), the mountain lions (green) and coyotes (blue) engage in conflict, suppressing the population of each. The mountain lions eventually win, sending the coyotes into extinction. A numeric solver was used to find the equilibrium that all three species approach.



Conclusion, Sources

While all three models share similar equilibrium points (between mountain lions and deer), behavior around these points differs substantially between models. Furthermore, each addition of complexity made our models more fragile. While both species refused to die in the first model, far more scenarios involved extinction in the third model. This could be due to the nature of natural ecosystems, or the nature of mathematical models.

- Dubey, B. and Upadhyay, R.K. *Persistence and Extinction of One-Prey and Two-Predators System*. Nonlinear Analysis: Modeling and Control, 2004, Vol 9, No. 4.
- Green et. al., *Reproductive Characteristics of Female White-Tailed Deer*, *Theriogenology*, Volume 94, 2017.
- Longhurst et. al., *The California Deer Decline and Possibilities for Restoration*, California Nevada Wildlife Transactions, Wildlife Society, 1976.
- Petorelli et. al., *Predation, Individual Variability and Vertebrate Population Dynamics*, *Oecologia*, 2011.
- Pierce, Becky et. al. *Selection of Mule Deer by Mountain Lions and Coyotes: Effects of Hunting Style, Body Size, and Reproductive Status*. "2000. *Journal of Mammalogy*, Volume 81, Issue 2.
- Xiao, Dongmei and Ruan, Shigui. *Global dynamics of a ratio-dependent predator-prey system*. *Journal of Mathematical Biology*, 2000.

Logistic Growth and Ratio Dependence

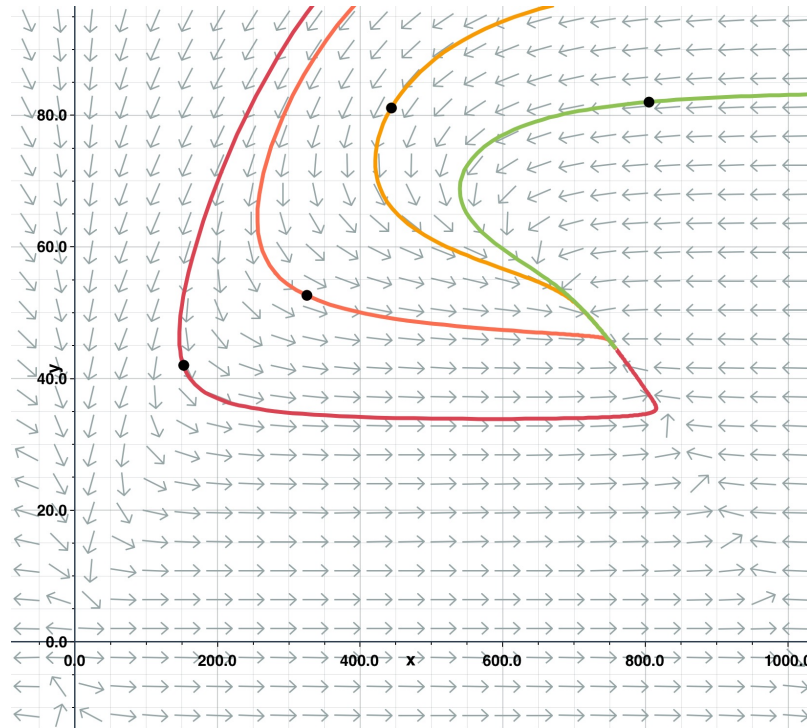
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Logistic growth is introduced by the addition of $(1-x/k)$ to the part of the equation controlling deer growth. This takes resource scarcity into account, and ensures that the deer population do not expand beyond its carrying capacity (k). The importance of this feature is highlighted by a potential behavior observable in the first model: without mountain lions the deer population will expand infinitely. While California's natural carrying capacity for deer is an unexpectedly contentious topic, the deer population peaked at approximately 2 million before declining substantially to its current level of 540,000.

Second Model Behavior

The phase plane of the second model is shown below. As the model is not linear, the Jacobian (matrix below) serves as a useful linear approximation.



Parameters:

$$a = 0.875, b = 1.8, c = 0.2,$$

$$d = 0.1, f = 0.44, k = 1000$$

Equilibrium points: (757, 44), (0,0), (1000, 0)

Jacobian:

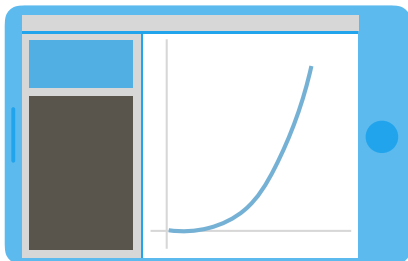
$$\begin{bmatrix} a - \frac{2ax}{k} - \frac{by(y+1)}{(fx+y+1)^2} & \frac{-bx(fx+1)}{(fx+y+1)^2} \\ \frac{dy(y+1)}{(fx+y+1)^2} & -c + \frac{dx(fx+1)}{(fx+y+1)^2} \end{bmatrix}$$

Using this Jacobian, the equilibrium points can be categorized. The Jacobian for the only equilibrium where both species survive is shown below, along with the useful indicators it provides.

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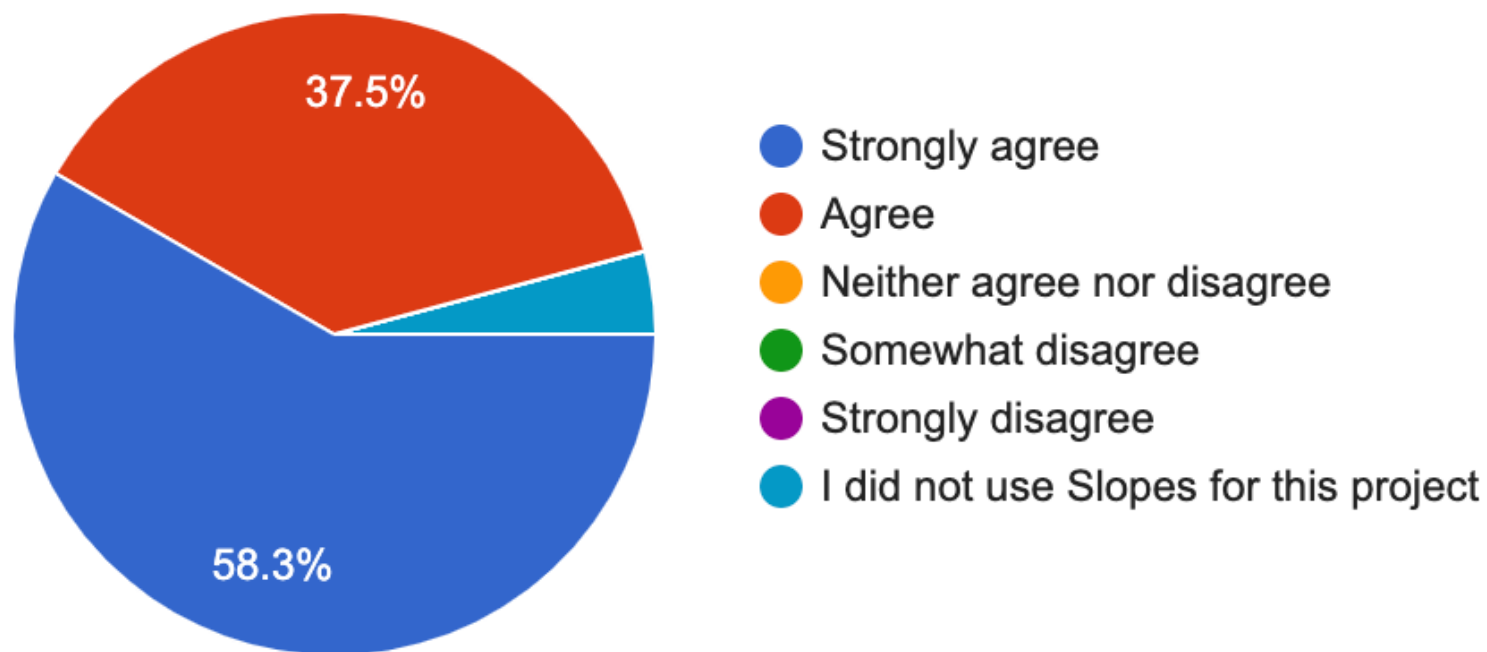
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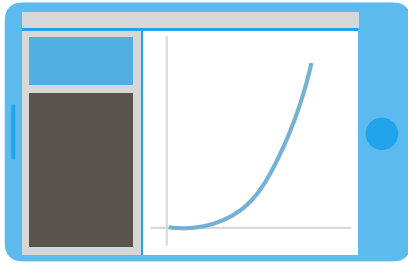
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Student Feedback

To what extent do you agree with the following statement: “I feel that using Slopes increased my understanding of the mathematical models in my project.”

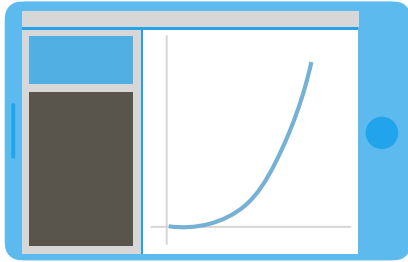




Student Feedback

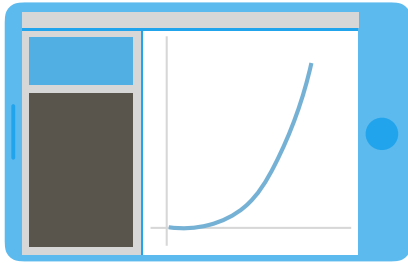
“It's good just because visualizing helps a lot to be able to understand, especially when you get to higher levels of math and things get kind of hard to understand sometimes.”

“I really love how interactive it is ...You can move it around and manipulate it. I like being able to click to see, okay, what does the solution with this initial condition look like?”



Acknowledgements

- * Student Developers
 - * Joshua Haug
 - * Frederick Jacques Joubert
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 - * Jereld Chng
 - * Frank Garcia
 - * David Nicholas
 - * Katelyn Pozon
 - * Charles Beck
- * Graphic Design: Dana Zurzolo
- * Comp Sci: Stan Warford



Questions?

Check out the apps at

<http://www.slopesapp.com>

<http://www.wavespdeapp.com>

