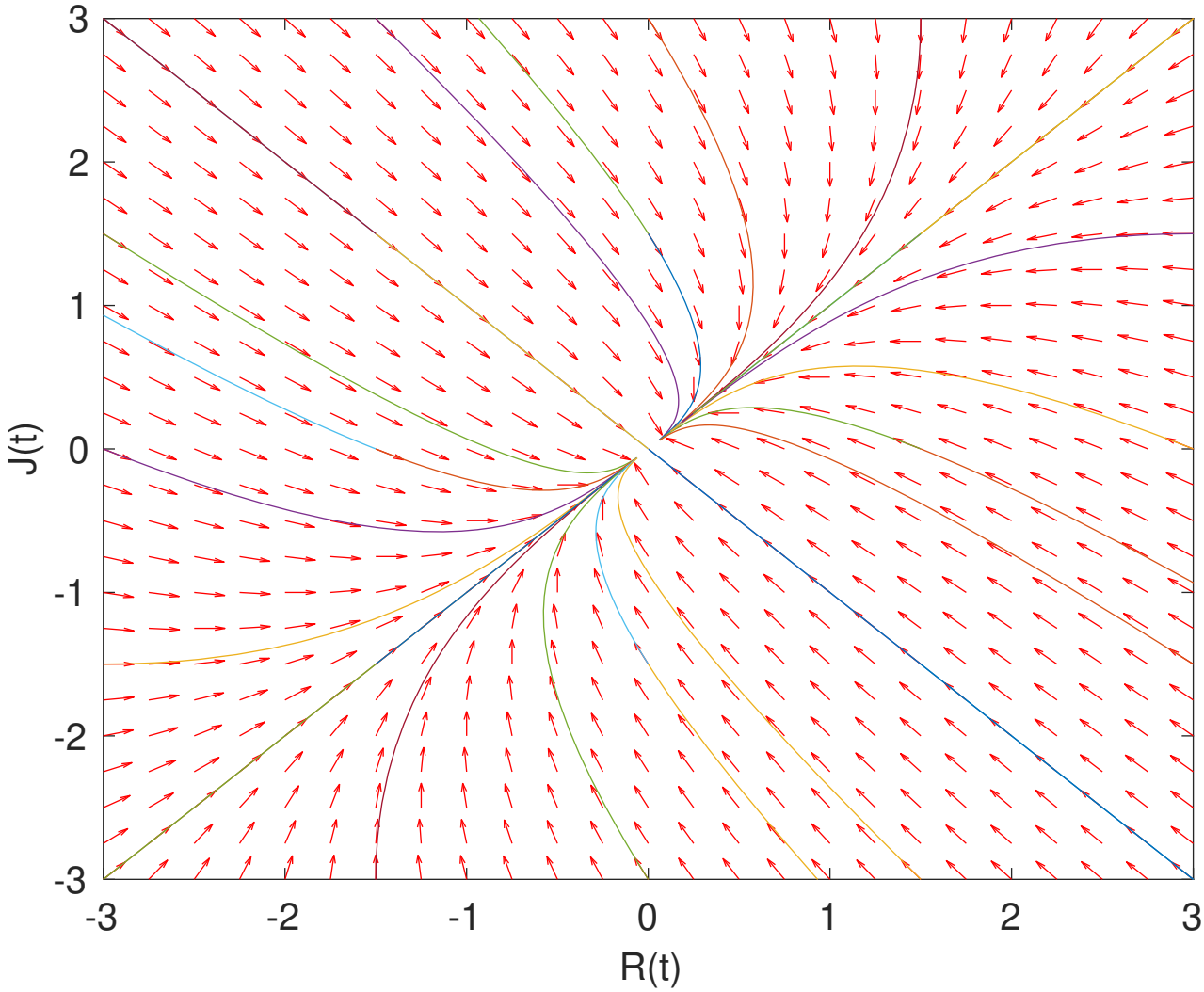
3
2
1
0
-1
-2
-3
J(t)
-3
-2
-1
0
1
2
3
R(t)