

**STUDENT VERSION**  
**CONJECTURING SOLUTIONS FOR LINEAR SYSTEM**  
**OF DIFFERENTIAL EQUATIONS**

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**Abstract:** We lead students from the solution for  $y(t) = k y(t)$  to a natural extension for the solution conjecture for a system of two constant coefficient, homogeneous, linear differential equations introducing eigenvalues and eigenvectors through student discovery.

**INTRODUCTION**

We consider a system of linear differential equations

$$\begin{aligned}x'(t) &= a x(t) + b y(t) \\y'(t) &= c x(t) + d y(t)\end{aligned}\tag{1}$$

with  $x(0) = x_0$  and  $y(0) = y_0$ .

We can put this in matrix form:

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} a x(t) + b y(t) \\ c x(t) + d y(t) \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \cdot \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}\tag{2}$$

with  $x(0) = x_0$  and  $y(0) = y_0$ .

OR

$$X'(t) = A \cdot X(t),$$

where

$$X'(t) = \begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix}, \quad A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \quad X(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} \quad (3)$$

$X'(t) = A \cdot X(t)$  is very suggestive for a solution of the form  $X(t) = ce^{At}$ . Thus one could conjecture a solution and try it out to see what  $c$  would have to be, but we have to remember  $A$  is a matrix, not a number, and while there are theories of what  $e^A$  would mean for a matrix  $A$  we choose not to go there now.

Instead, we conjecture a vector solution for  $X(t)$  which has the best of both worlds (1) nice exponential form with no matrices in the exponent and (2) vector status where we can see the pieces of the solution:

$$X(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} u \\ v \end{bmatrix} \cdot e^{\lambda t}. \quad (4)$$

So here we are suggesting  $x(t) = ue^{\lambda t}$  and  $y(t) = ve^{\lambda t}$ .

### Assignment

1. Now put the conjecture (4) in (3) and see what has to happen to  $a, b, c, d$  and  $u, v$  in order to obtain solutions - interesting solutions, i.e. other than  $u = 0$  and  $v = 0$ . Go for it!!! Summarize your conclusions in a nice write-up
2. Illustrate the solution strategy from assignment (1) using the following system

$$\begin{aligned} x'(t) &= -4x(t) - 2y(t) \\ y'(t) &= -1x(t) - 3y(t) \end{aligned} \quad (5)$$

with  $x(0) = 2$  and  $y(0) = 1$ .